

#### STOMPBOX DESIGN WORKSHOP

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CCRMA - Stanford University
July 2011

### **FX Basics: Dynamics Effects**

Dynamics effects were the **earliest effects** to be introduced by guitarists.

The simple idea behind dynamics effects is to amplify or attenuate the amplitude of the electrical signal coming out from the pickup or microphone.

They first appeared in the 1940s as simple on/off switch boards, evolving to volume pedals in the 1950s.

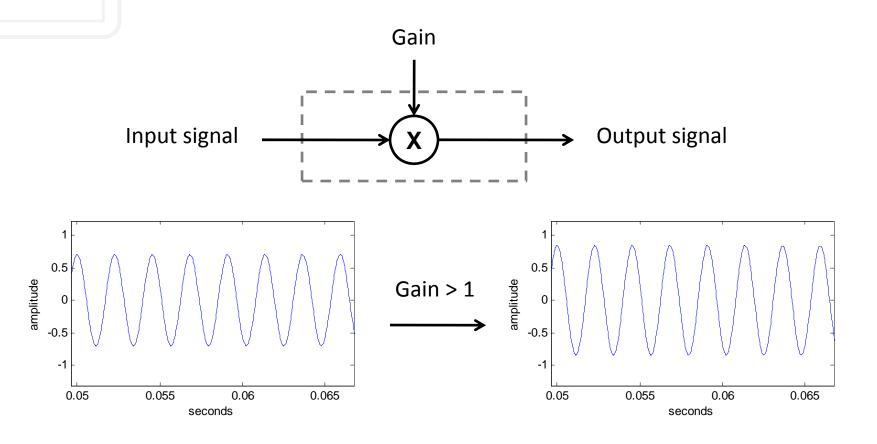
Ex: volume pedal, boost, tremolo, noise gate, dynamic range compressor

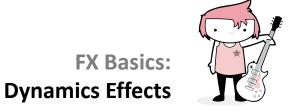




### **Gain control**

Achieved by means of a simple multiplication.

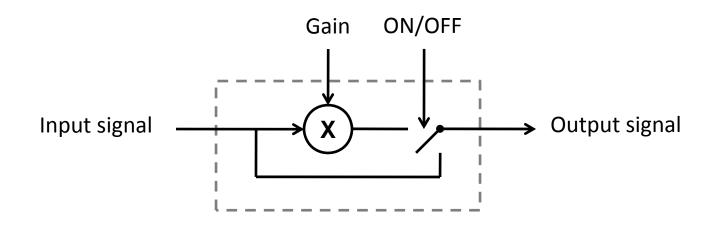


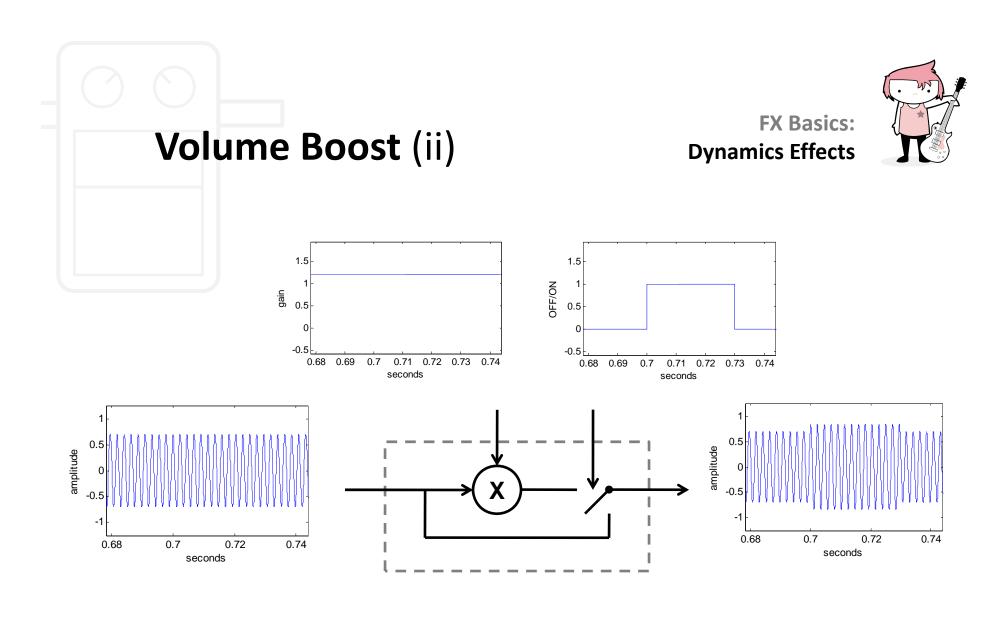


### **Volume Boost**

Generally used for *boosting* volume during solos and/or preventing signal loss in long *effect chains*.

Ex: when switching from rhythm guitar to lead guitar, a guitarist may use a clean boost to increase the volume of his or her solo.





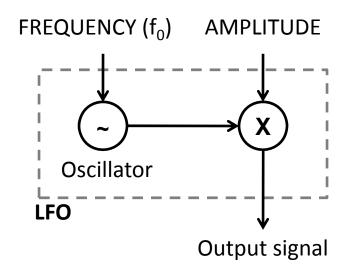
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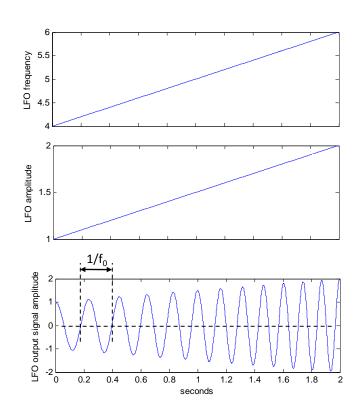


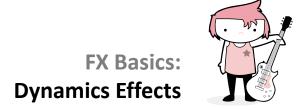
### **Tremolo**

Produces a slight, rapid oscillation of the signal amplitude; not to be confused with *tremolo bar* (pitch oscillation).

Based on the use of a Low Frequency Oscillator (LFO):





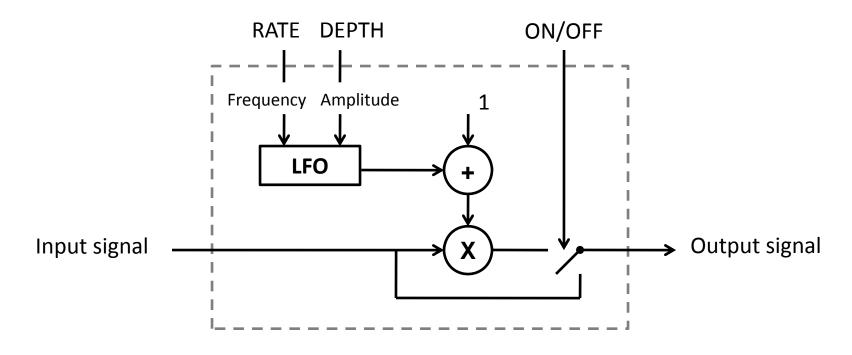


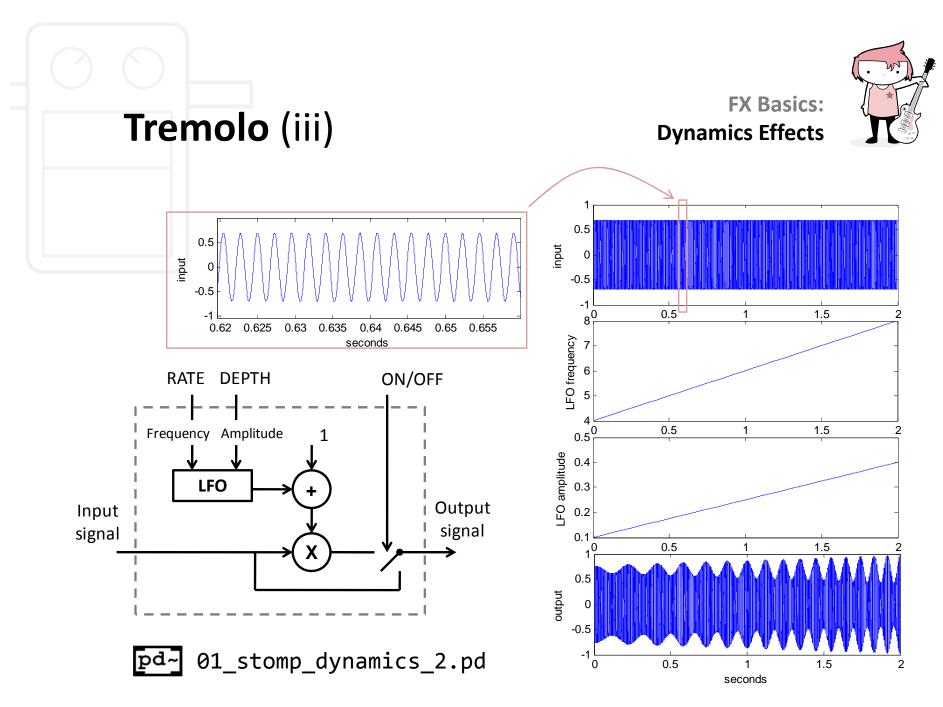
# Tremolo (ii)

Typically, two controls are offered:

RATE: Sets the frequency of the volume oscillation

DEPTH: Sets the amplitude of the volume oscillation





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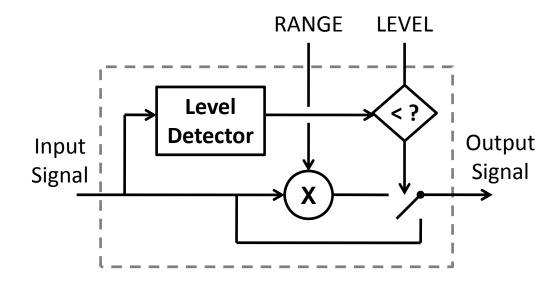
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# Noise gate

Attenuates signal when its level falls below a given threshold. Both the attenuation and threshold are usually available as user controls (resp. RANGE and LEVEL).

Ex: avoid unwanted noise floor when there is no signal coming from the instrument



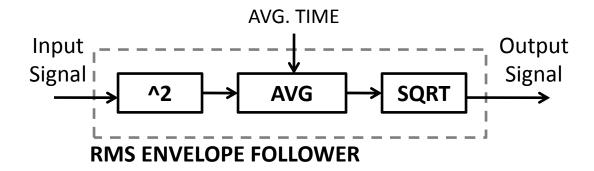


## Noise gate (ii)

#### **LEVEL DETECTOR** (Envelope Follower):

Often implemented as <u>Root Mean Square</u> (RMS) meter. RMS amplitude provides a measure of effective (short-time averaged) signal intensity.

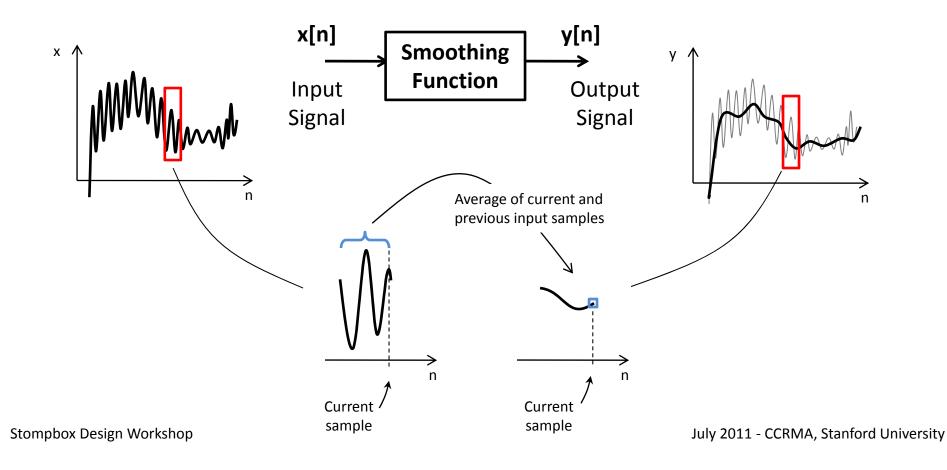
'Averaging time' sets the responsiveness of the meter.

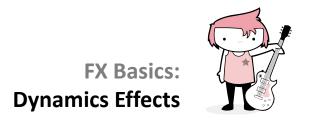




#### **TIME AVERAGE**

Acts as a smoothing function:





#### **TIME AVERAGE:**

$$y[n] = (1/M) \cdot (x[n] + x[n-1] + ... + x[n-M+1] + x[n-M])$$

Obtain M from 'averaging time' :  $M = avgTime \cdot f_s$ 

#### **SMOOTHING WITH RECURSIVE EQUATION:**

Find coefficients **a** and **b** so that equation

$$y[n] = b_0 \cdot x[n] + b_1 \cdot x[n-1] + ... + b_N \cdot x[n-N] \leftarrow \text{current and previous input samples}$$

$$-a_1 \cdot y[n-1] - ... - a_N \cdot y[n-N] \leftarrow previous output samples$$

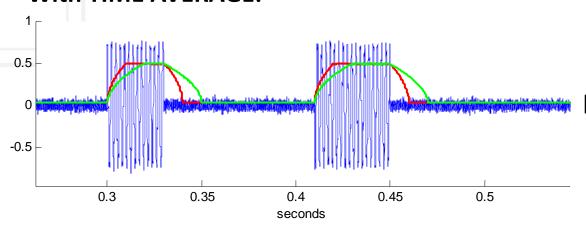
results into a smoothing function.

...digital implementation of a <u>Low Pass</u> (**LP**) filter.



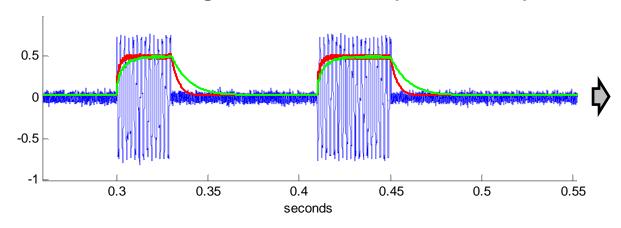
#### RMS Envelope...

#### With TIME AVERAGE:

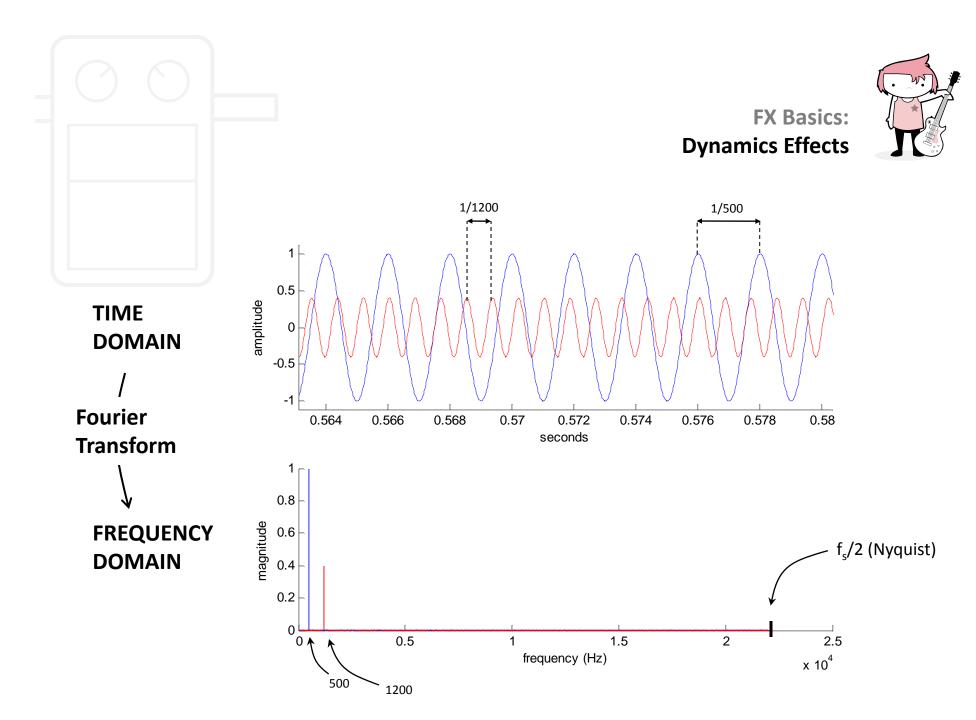


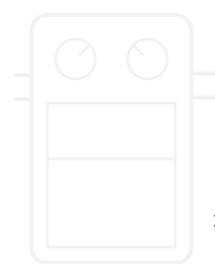
Averaging using
441 and 882 previous
samples respectively
(M=441; M=882)

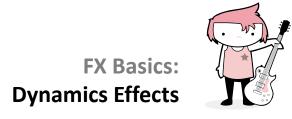
#### With Smoothing Low-Pass Filter (RECURSIVE):



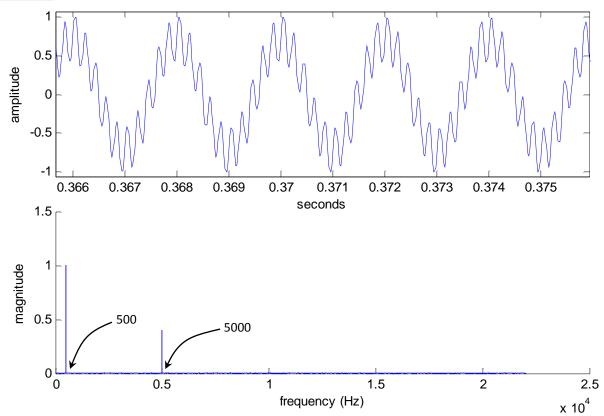
Both filters only using **1 previous sample** (N=1)!!

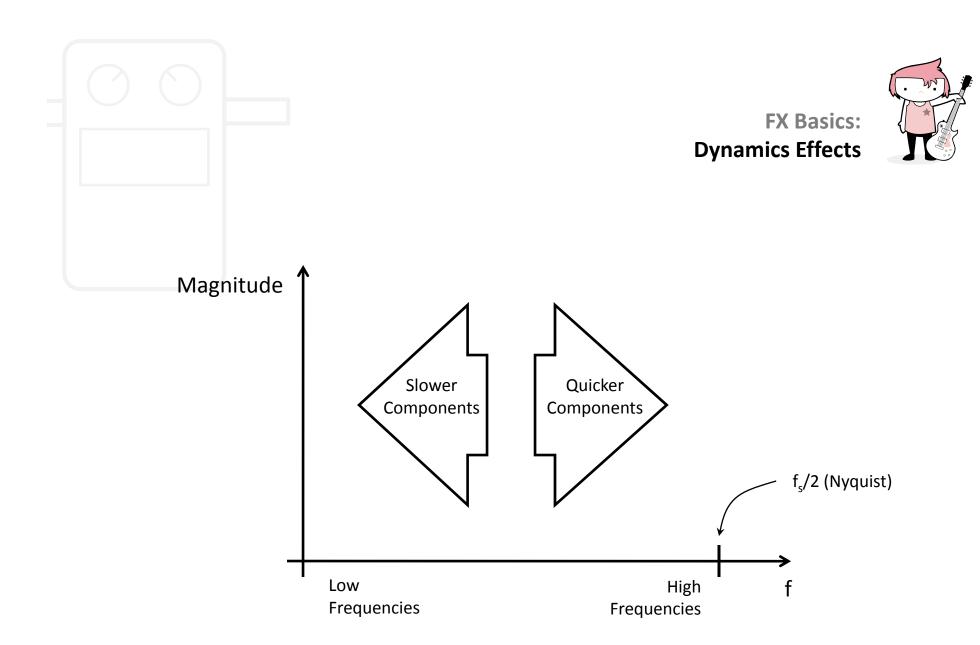




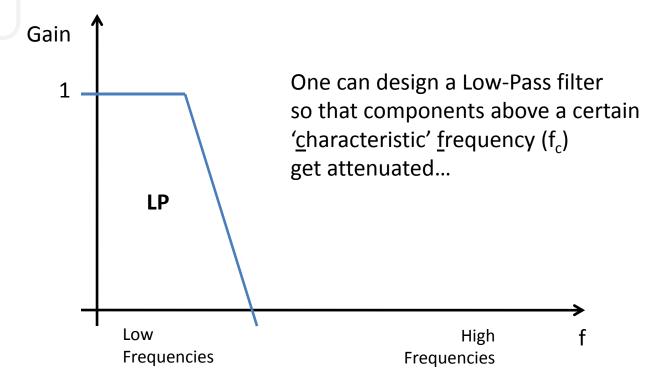


#### $x(t) = 1.0 \cdot \sin(2 \cdot \pi \cdot 500 \cdot t) + 0.4 \cdot \sin(2 \cdot \pi \cdot 5000 \cdot t)$





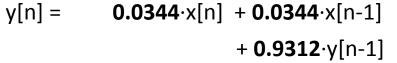


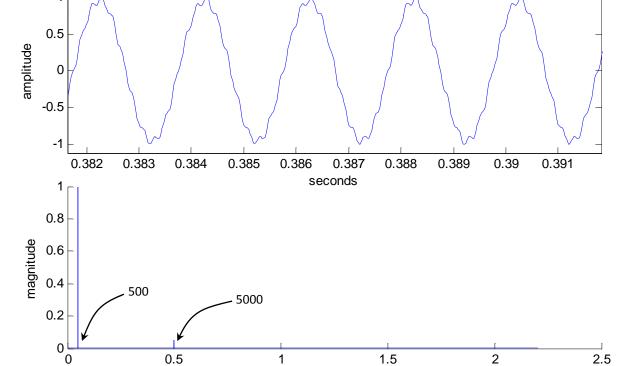




# **FX Basics:**

# **Dynamics Effects**



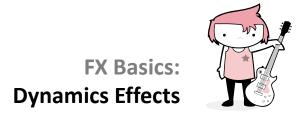


frequency (Hz)

How to 'design' the coefficients? (e.g. how many coefficients? which values?)

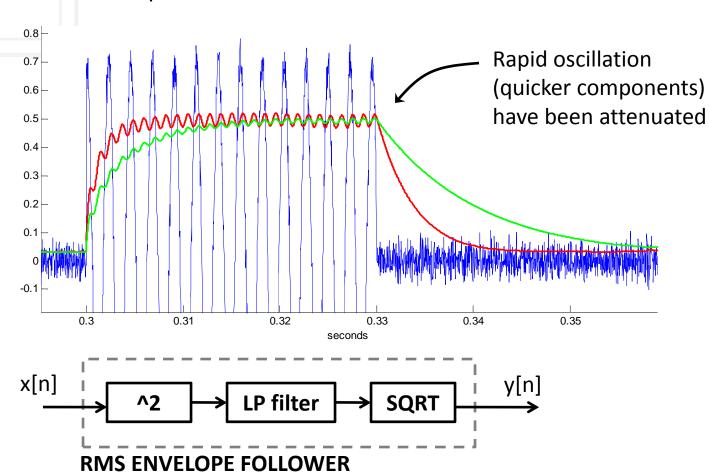
> Basics of **DIGITAL FILTERS** (to come...)

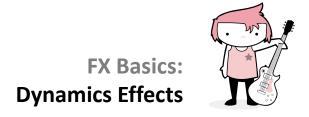
x 10<sup>4</sup>



## Noise gate (iii)

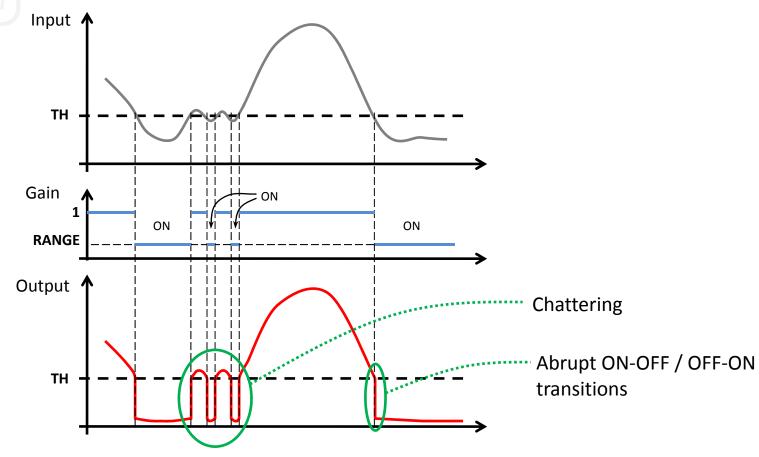
#### RMS Envelope Follower





# Noise gate (iv)

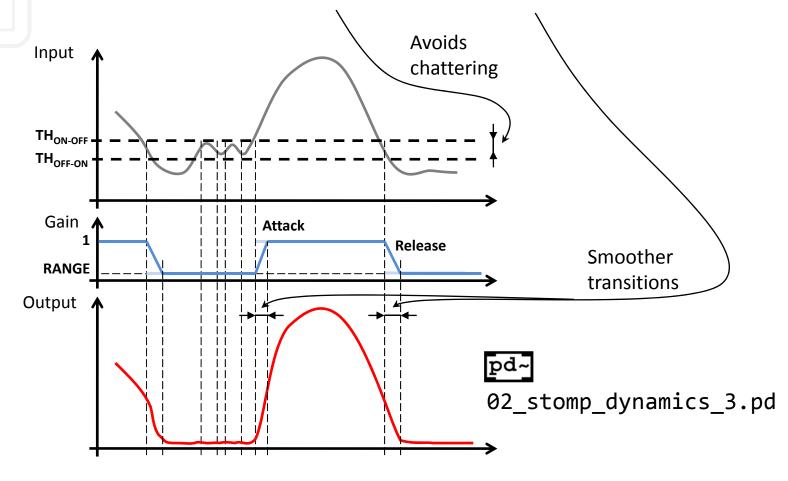
Example of basic operation

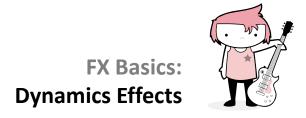




# Noise gate (v)

Noise gates often include HYSTERESIS and ATTACK/RELEASE times

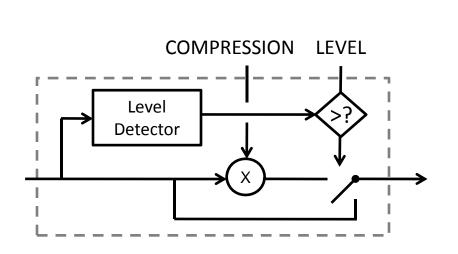


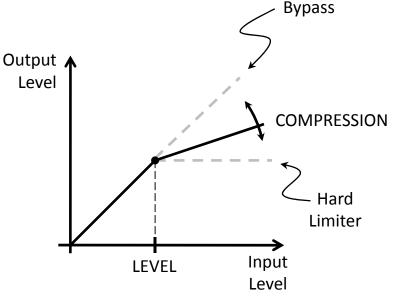


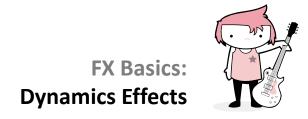
# Dynamic Range Compressor

Attenuates the signal when its level its higher than a certain threshold. Both the amount of attenuation and the threshold are the most typical user controls (resp. COMPRESSION/RATIO and LEVEL).

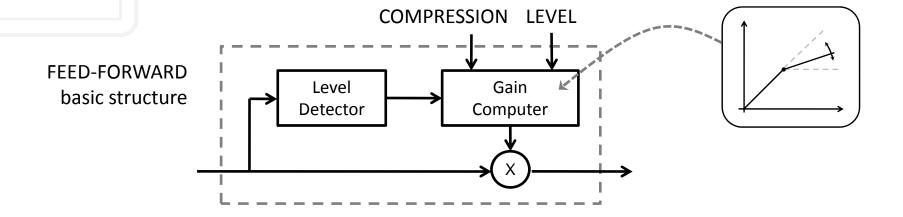
Ex: reduce intensity differences, soften the amplitude of very loud attacks

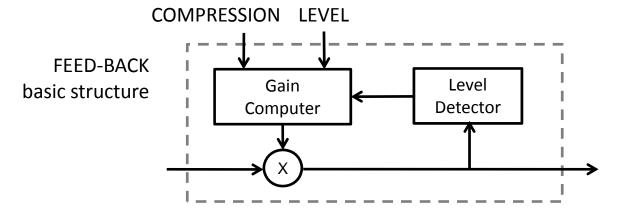


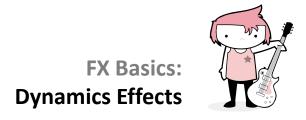




# **Dynamic Range Compressor** (ii)

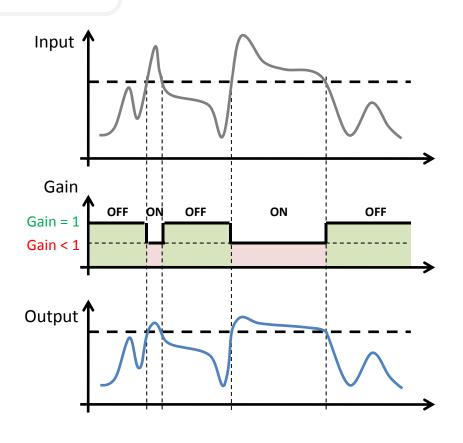


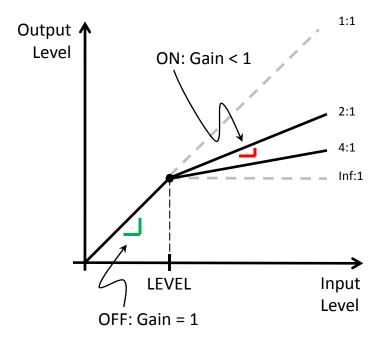


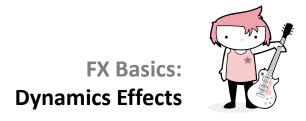


# **Dynamic Range Compressor** (iii)

Example of basic operation







# **Dynamic Range Compressor** (iv)

Further available controls, depending on application:

- ATTACK / RELEASE TIMES
- HARD vs SOFT KNEE
- MAKE-UP GAIN

