



MACHINE LEARNING: CLUSTERING, AND CLASSIFICATION

Steve Tjoa
kiemyang@gmail.com

June 2013

Review from Day 2

Review from Day 2

Review from Day 2

- How did the lab go?

Review from Day 2

- How did the lab go?
- Did you try other audio files – other instrument recognizers?

Review from Day 2

- How did the lab go?
- Did you try other audio files – other instrument recognizers?
- Cross Validation?

Supervised vs. Unsupervised

- Unsupervised – “clustering”
- Supervised – binary classifiers (2 classes)
- Multiclass is derived from binary

Clustering

- Unsupervised learning – find pockets of data to group together
- Statistical analysis techniques

Clustering

- $K = \#$ of clusters
- Choosing the number of clusters – note that choosing the “best” number of clusters according to minimizing total squared distance will always result in same $\#$ of clusters as data points.

Clustering

The basic goal of clustering is to divide the data into groups such that the points within a group are close to each other, but far from items in other groups.

Hard clustering – each point is assigned to one and only one cluster.

K-Means

The key points relating to k-means clustering are:



K-Means

The key points relating to k-means clustering are:

- k-means is an automatic procedure for clustering unlabelled data;



K-Means

The key points relating to k-means clustering are:

- k-means is an automatic procedure for clustering unlabelled data;
- it requires a pre-specified number of clusters;



K-Means

The key points relating to k-means clustering are:

- k-means is an automatic procedure for clustering unlabelled data;
- it requires a pre-specified number of clusters;
- Clustering algorithm chooses a set of clusters with the minimum within-cluster variance



K-Means

The key points relating to k-means clustering are:

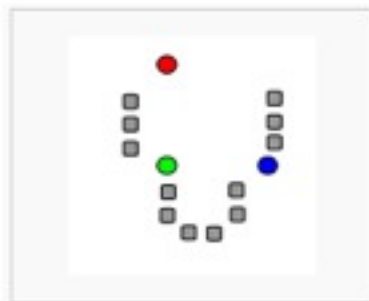
- k-means is an automatic procedure for clustering unlabelled data;
- it requires a pre-specified number of clusters;
- Clustering algorithm chooses a set of clusters with the minimum within-cluster variance
- Guaranteed to converge (eventually)



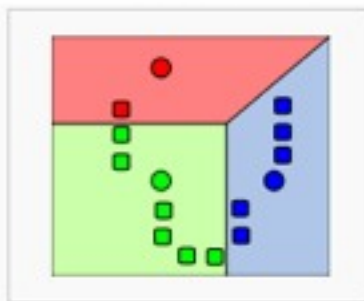
Demo

- http://home.dei.polimi.it/matteucc/Clustering/tutorial_html/AppletKM.html

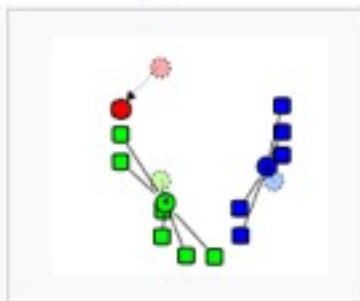
Demonstration of the standard algorithm



1) k initial "means" (in this case $k=3$) are randomly selected from the data set (shown in color).



2) k clusters are created by associating every observation with the nearest mean. The partitions here represent the [Voronoi diagram](#) generated by the means.



3) The [centroid](#) of each of the k clusters becomes the new means.



4) Steps 2 and 3 are repeated until convergence has been reached.

K-Means

The initialization method needs to be further specified. There are several possible ways to initialize the cluster centers:

K-Means

The initialization method needs to be further specified. There are several possible ways to initialize the cluster centers:

- Choose random data points as cluster centers

K-Means

The initialization method needs to be further specified. There are several possible ways to initialize the cluster centers:

- Choose random data points as cluster centers
- Randomly assign data points to K clusters and compute means as initial centers

K-Means

The initialization method needs to be further specified. There are several possible ways to initialize the cluster centers:

- Choose random data points as cluster centers
- Randomly assign data points to K clusters and compute means as initial centers
- Choose data points with extreme values

K-Means

The initialization method needs to be further specified. There are several possible ways to initialize the cluster centers:

- Choose random data points as cluster centers
- Randomly assign data points to K clusters and compute means as initial centers
- Choose data points with extreme values
- Find the mean for the whole data set then perturb into k means



ANALYSIS AND DECISION MAKING: GMMS

Mixture Models (GMM)

- K-means = hard clusters.
- GMM = soft clusters.

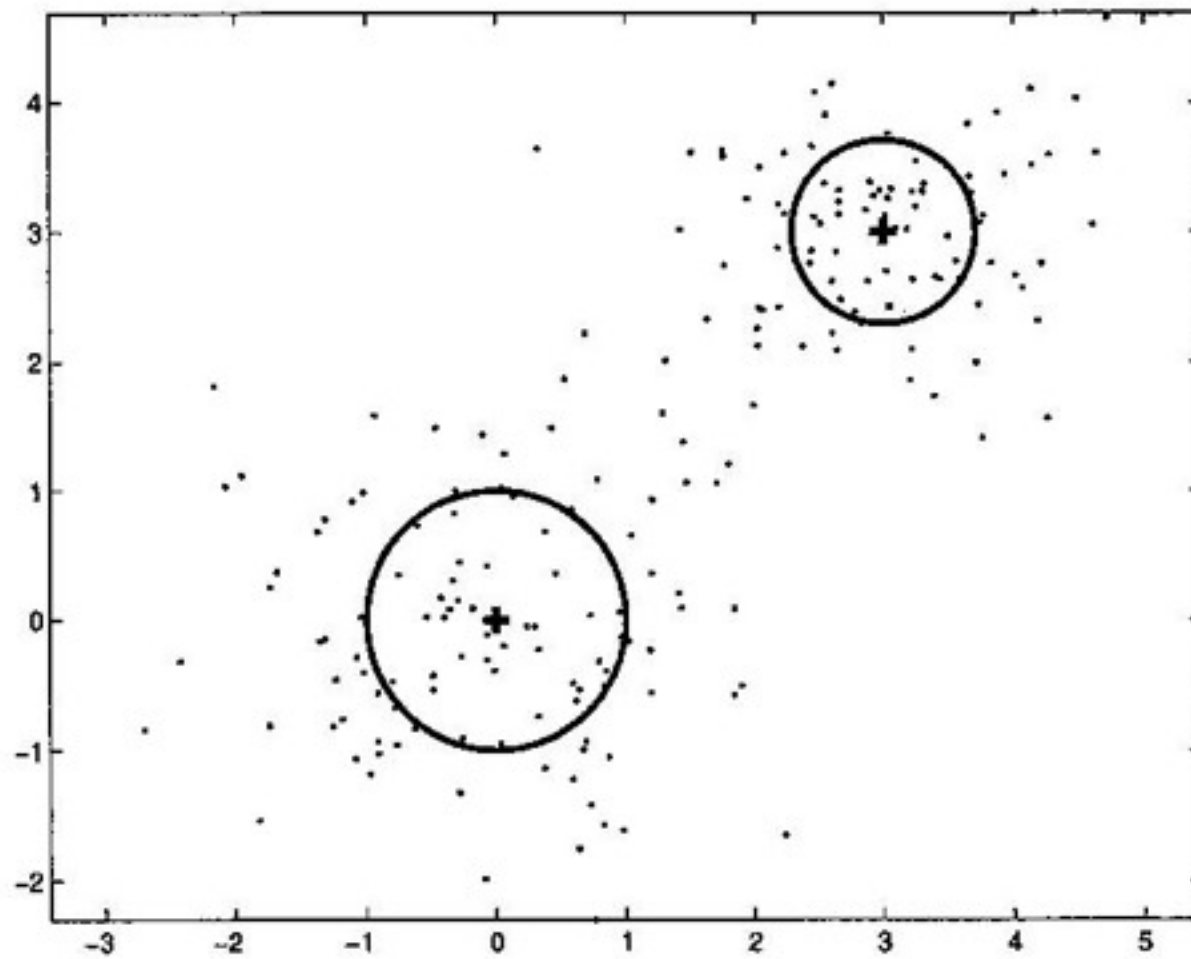


Fig. 3.1. Spherical covariance mixture model. Sampled data (*dots*), centres (*crosses*) and one standard deviation error bars (*lines*).

Mixture Models (GMM)

- GMM is good because:
 1. Can approximate any pdf with enough components
 2. EM makes it easy to find components parameters
 - EM – the means and variances adapt to fit the data as well as possible
 3. Compresses data considerably
- Can make softer decisions (decide further downstream given additional information)



GMM Parameters



GMM Parameters

Input



GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3



GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3
- Mixture coefficients (sum = 1)
 - e.g., [0.5 0.2 0.3]
 - “Priors” or “Prior probabilities”
 - Priors are “the **original** probability that each point came from a given mixture.”
 - “A prior is often the purely subjective assessment of an experienced expert.”

GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3
- Mixture coefficients (sum = 1)
 - e.g., [0.5 0.2 0.3]
 - “Priors” or “Prior probabilities”
 - Priors are “the **original** probability that each point came from a given mixture.”
 - “A prior is often the purely subjective assessment of an experienced expert.”
- Initialized centers, means, variances. (optional)

GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3
- Mixture coefficients (sum = 1)
 - e.g., [0.5 0.2 0.3]
 - “Priors” or “Prior probabilities”
 - Priors are “the **original** probability that each point came from a given mixture.”
 - “A prior is often the purely subjective assessment of an experienced expert.”
- Initialized centers, means, variances. (optional)

Output

GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3
- Mixture coefficients (sum = 1)
 - e.g., [0.5 0.2 0.3]
 - “Priors” or “Prior probabilities”
 - Priors are “the **original** probability that each point came from a given mixture.”
 - “A prior is often the purely subjective assessment of an experienced expert.”
- Initialized centers, means, variances. (optional)

Output

- Component centers/means, variances, and mixture coeff.

GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3
- Mixture coefficients (sum = 1)
 - e.g., [0.5 0.2 0.3]
 - “Priors” or “Prior probabilities”
 - Priors are “the **original** probability that each point came from a given mixture.”
 - “A prior is often the purely subjective assessment of an experienced expert.”
- Initialized centers, means, variances. (optional)

Output

- Component centers/means, variances, and mixture coeff.
- Posterior probabilities
 - “Posterior probabilities are the responsibilities which the Gaussian components have for each of the data points.”

GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3
- Mixture coefficients (sum = 1)
 - e.g., [0.5 0.2 0.3]
 - “Priors” or “Prior probabilities”
 - Priors are “the **original** probability that each point came from a given mixture.”
 - “A prior is often the purely subjective assessment of an experienced expert.”
- Initialized centers, means, variances. (optional)

Output

- Component centers/means, variances, and mixture coeff.
- Posterior probabilities
 - “Posterior probabilities are the responsibilities which the Gaussian components have for each of the data points.”

Query

GMM Parameters

Input

- Number of components (Gaussians)
 - e.g., 3
- Mixture coefficients (sum = 1)
 - e.g., [0.5 0.2 0.3]
 - “Priors” or “Prior probabilities”
 - Priors are “the **original** probability that each point came from a given mixture.”
 - “A prior is often the purely subjective assessment of an experienced expert.”
- Initialized centers, means, variances. (optional)

Output

- Component centers/means, variances, and mixture coeff.
- Posterior probabilities
 - “Posterior probabilities are the responsibilities which the Gaussian components have for each of the data points.”

Query

- Obtain similarity via Likelihood



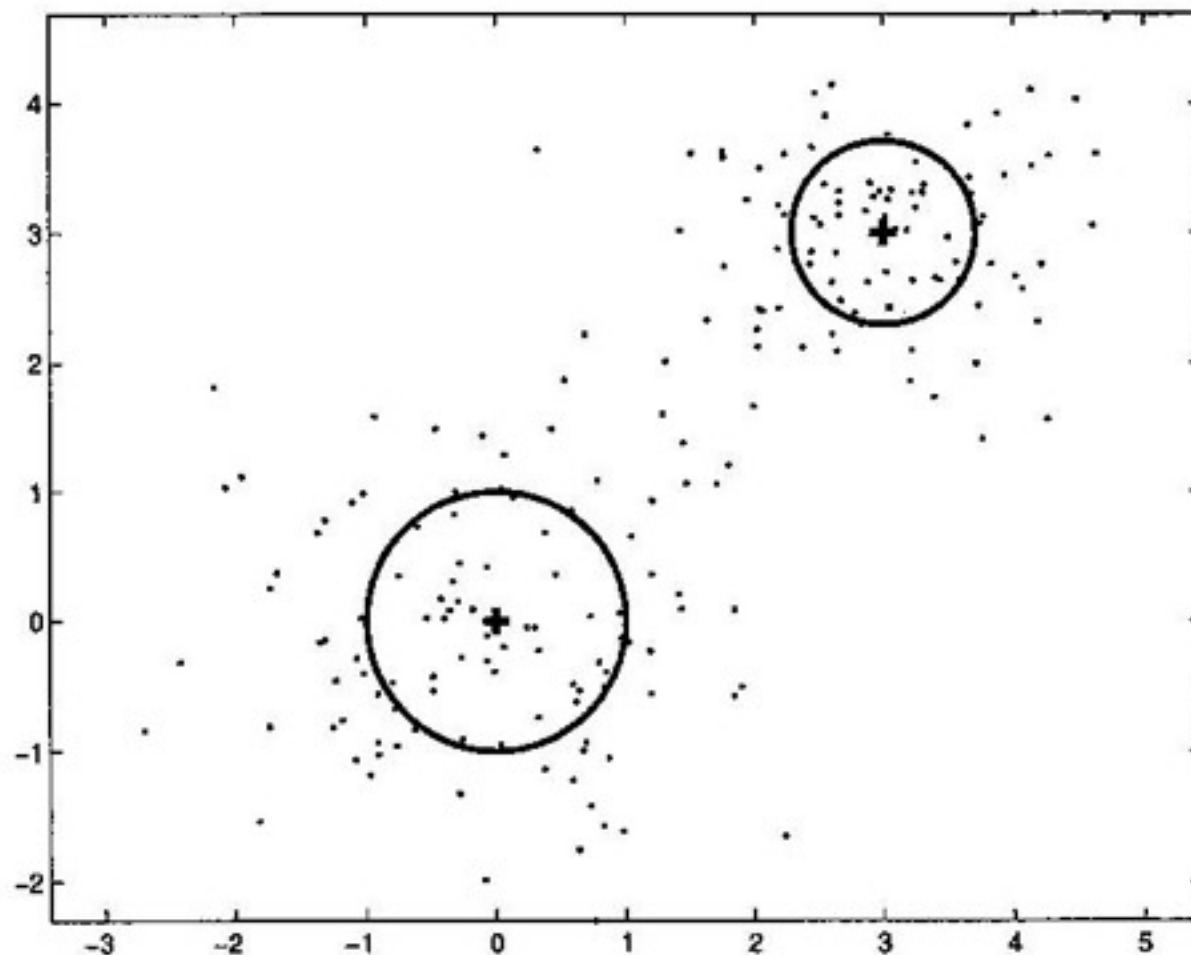


Fig. 3.1. Spherical covariance mixture model. Sampled data (*dots*), centres (*crosses*) and one standard deviation error bars (*lines*).

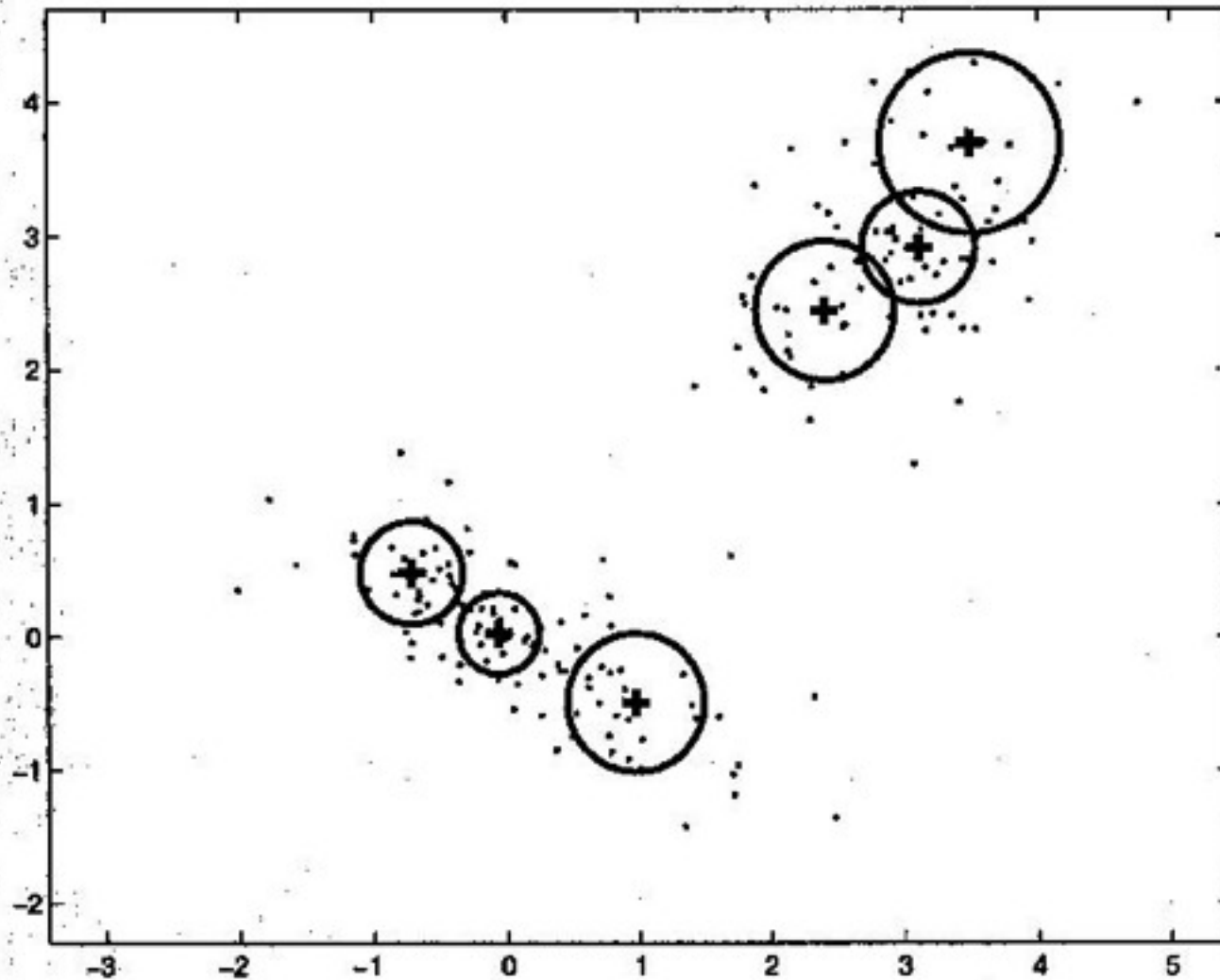


Fig. 4. Spherical covariance mixture model with six components fitted to the sampled data from the full covariance two-component model in Fig. 3.3. Sampled data (dots), centres (crosses) and one standard deviation error bars (lines).

- From Netlab (p82-83)

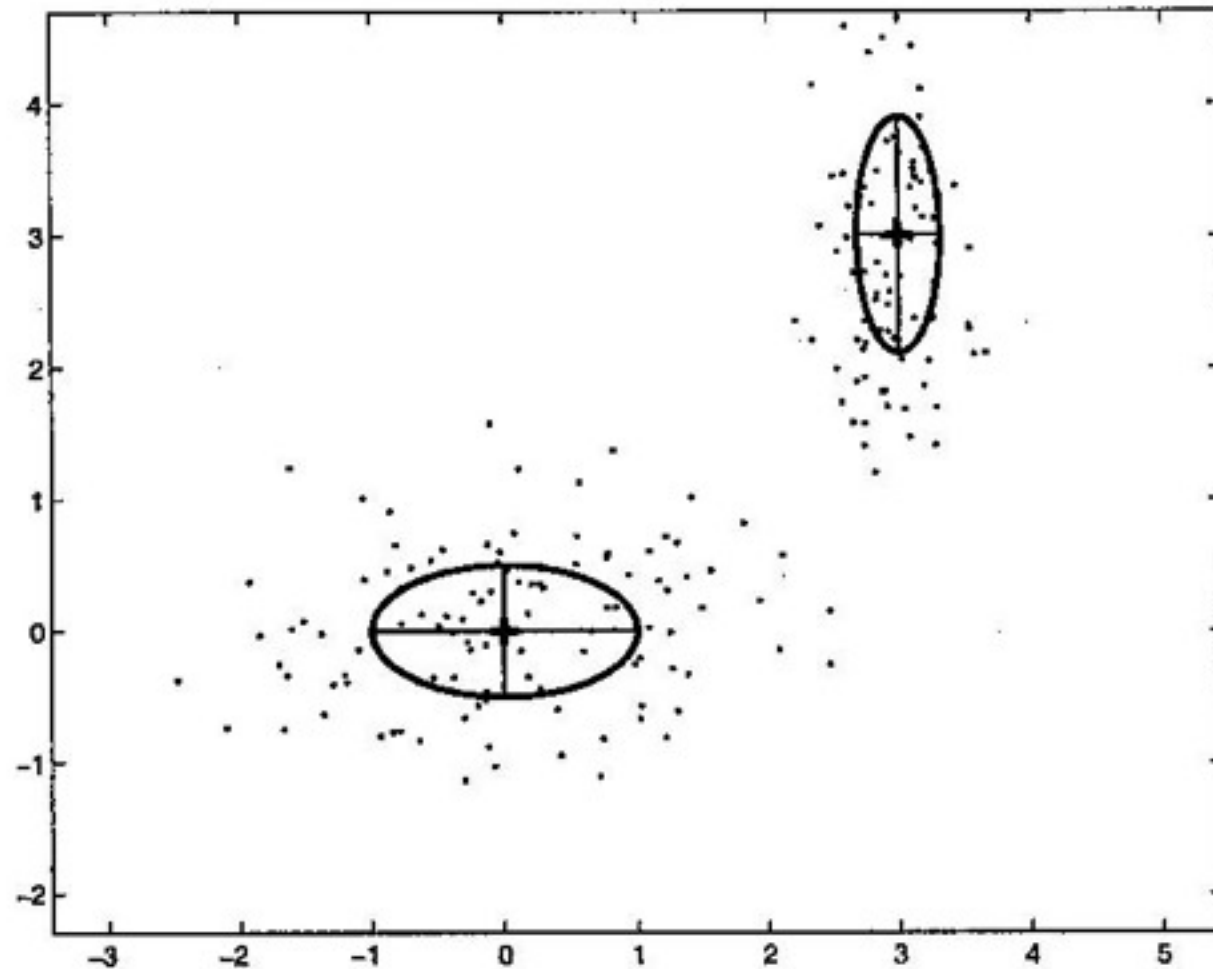
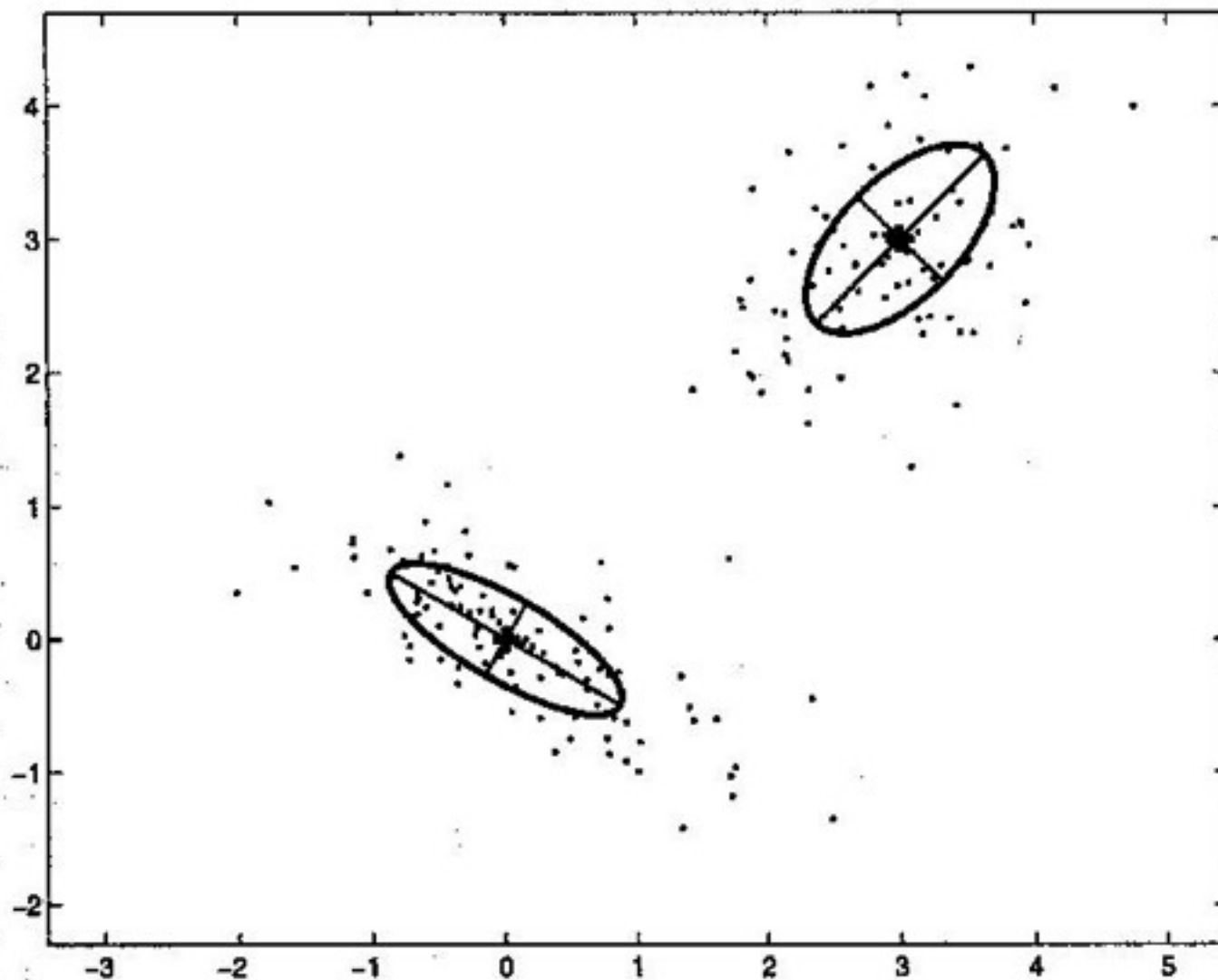


Fig. 3.2. Diagonal covariance mixture model. Sampled data (*dots*), centre (*crosses*), covariance axes (*thin lines*) and one standard deviation error bars (*thick lines*).



3. Full covariance mixture model. Sampled data (*dots*), centres (*crosses*), principal axes (*thin lines*) and one standard deviation error bars (*thick lines*).

GMM

- “Pooled covariance” – using a single covariance to describe all clusters (saves on parameter computation)

GMM: Likelihood

1. Evaluate the probability of that mixture modeling your point.



GMM: Likelihood

1. Evaluate the probability of that mixture modeling your point.

```
likelihoodgm1 = gmmprob  
(gm1,testing_features)
```



GMM: Likelihood

1. Evaluate the probability of that mixture modeling your point.

```
likelihoodgm1 = gmmprob  
(gm1,testing_features)  
likelihoodgm2 = gmmprob  
(gm2,testing_features);
```



GMM: Likelihood

1. Evaluate the probability of that mixture modeling your point.

```
likelihoodgm1 = gmmprob  
(gm1,testing_features)  
likelihoodgm2 = gmmprob  
(gm2,testing_features);  
loglikelihood = log(likelihoodKick ./  
likelihoodSnare )
```



GMM: Likelihood

1. Evaluate the probability of that mixture modeling your point.

```
likelihoodgm1 = gmmprob  
(gm1,testing_features)  
likelihoodgm2 = gmmprob  
(gm2,testing_features);  
loglikelihood = log(likelihoodKick ./  
likelihoodSnare )
```



GMM: Likelihood

1. Evaluate the probability of that mixture modeling your point.

```
likelihoodgm1 = gmmprob  
(gm1,testing_features)  
likelihoodgm2 = gmmprob  
(gm2,testing_features);  
loglikelihood = log(likelihoodKick ./  
likelihoodSnare )
```

- Log-function is “order-preserving” – maximizing a function vs. maximizing its log



Minimization Problems

> Demgmm1

Minimization Problems

> Demgmm1

- EM is gradient-based – it does not find the global maximum in the general case, unless properly initialized in the general region of interest.

Minimization Problems

> Demgmm1

- EM is gradient-based – it does not find the global maximum in the general case, unless properly initialized in the general region of interest.

Minimization Problems

> Demgmm1

- EM is gradient-based – it does not find the global maximum in the general case, unless properly initialized in the general region of interest.
- Error wants to be $-\infty$, which occurs when Gaussian is fit for each data point. (mean = data point and variance = 0)

Minimization Problems

> Demgmm1

- EM is gradient-based – it does not find the global maximum in the general case, unless properly initialized in the general region of interest.
- Error wants to be $-\infty$, which occurs when Gaussian is fit for each data point. (mean = data point and variance = 0)

Minimization Problems

> Demgmm1

- EM is gradient-based – it does not find the global maximum in the general case, unless properly initialized in the general region of interest.
- Error wants to be $-\infty$, which occurs when Gaussian is fit for each data point. (mean = data point and variance = 0)
- “There are often a large number of local minima which correspond to poor models. Solution is to build models from many different initialization

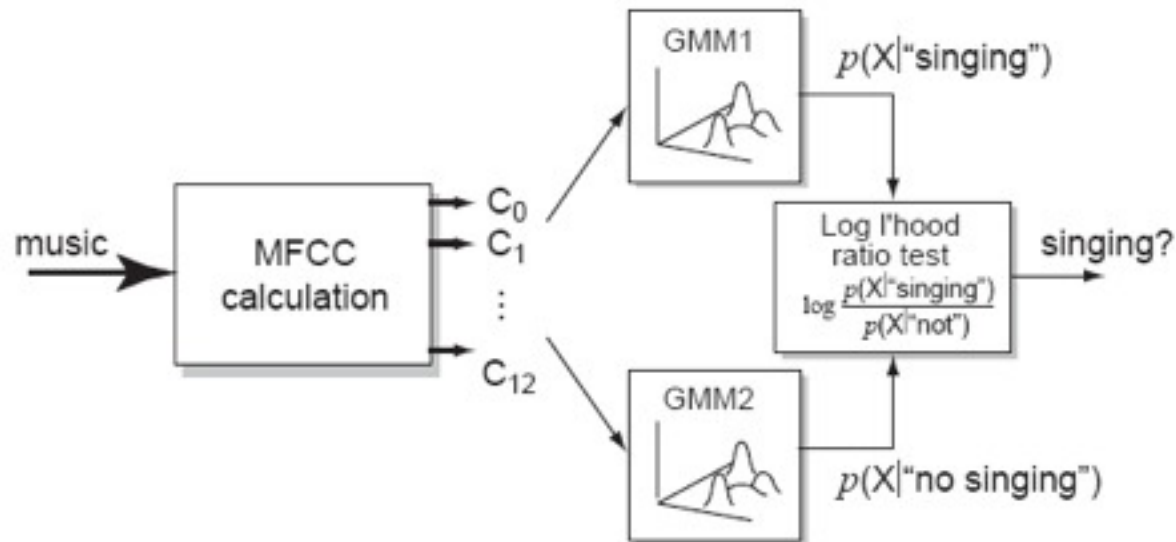
GMM

- Application:
 - State-of-the-art speech recognition systems
 - estimate up to 30,000 separate GMMs, each with about 32 components. This means that these systems can have up to a million Gaussian components!! All the parameters are estimated from (a lot of) data by the EM algorithm.

Application:
Speaker Recognition

GMM System

- **Separate models for $p(x|sing)$, $p(x|no\ sing)$**
 - combined via likelihood ratio test



- **How many Gaussians for each?**
 - say 20; depends on data & complexity
- **What kind of covariance?**
 - diagonal (spherical?)



Genre

“Because feature vectors are computed from short segments of audio, an entire song induces a cloud of points in feature space.”



Genre

“Because feature vectors are computed from short segments of audio, an entire song induces a cloud of points in feature space.”

“The cloud can be thought of as samples from a distribution that characterizes the song, and we can model that distribution using statistical techniques. Extending this idea, we can conceive of a distribution in feature space that characterizes the entire repertoire of each artist.”



Genre

“Because feature vectors are computed from short segments of audio, an entire song induces a cloud of points in feature space.”

“The cloud can be thought of as samples from a distribution that characterizes the song, and we can model that distribution using statistical techniques. Extending this idea, we can conceive of a distribution in feature space that characterizes the entire repertoire of each artist.”



Genre

“Because feature vectors are computed from short segments of audio, an entire song induces a cloud of points in feature space.”

“The cloud can be thought of as samples from a distribution that characterizes the song, and we can model that distribution using statistical techniques. Extending this idea, we can conceive of a distribution in feature space that characterizes the entire repertoire of each artist.”

A. Berenzweig, B. Logan, D. Ellis, and B. Whitman. A large-scale evaluation



Genre

“Because feature vectors are computed from short segments of audio, an entire song induces a cloud of points in feature space.”

“The cloud can be thought of as samples from a distribution that characterizes the song, and we can model that distribution using statistical techniques. Extending this idea, we can conceive of a distribution in feature space that characterizes the entire repertoire of each artist.”

A. Berenzweig, B. Logan, D. Ellis, and B. Whitman. A large-scale evaluation of acoustic and subjective music similarity measures. In Proceedings



Genre

“Because feature vectors are computed from short segments of audio, an entire song induces a cloud of points in feature space.”

“The cloud can be thought of as samples from a distribution that characterizes the song, and we can model that distribution using statistical techniques. Extending this idea, we can conceive of a distribution in feature space that characterizes the entire repertoire of each artist.”

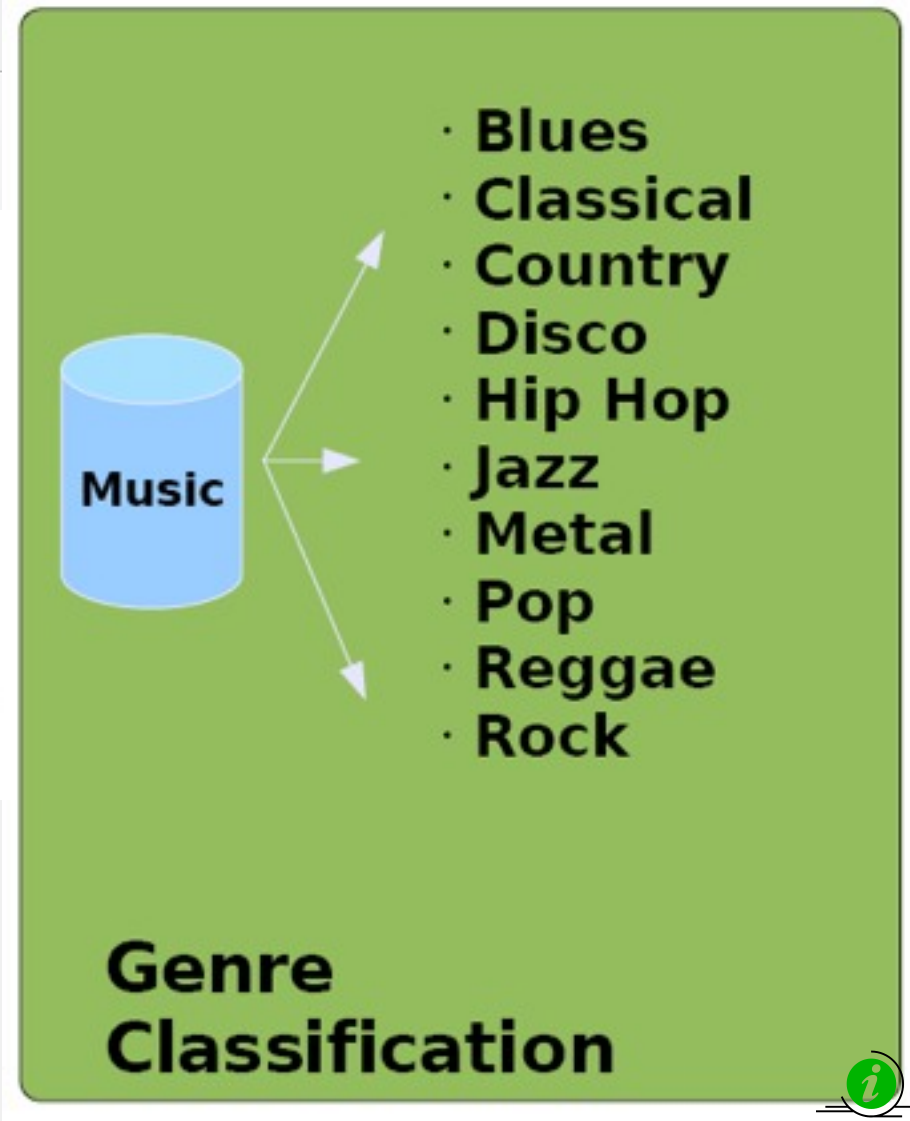
A. Berenzweig, B. Logan, D. Ellis, and B. Whitman. A large-scale evaluation of acoustic and subjective music similarity measures. In Proceedings of 4th International Symposium on Music Information Retrieval,



- **Genre Classification:**

- Manual : 72%
(Perrot/Gjerdigen)
- Automated (2002) 60%
(Tzanetakis)
- Automated (2005) 82%
(Bergstra/Casagrande/Eck)
- Automated (2007) 76%

*From ISMIR 2007 Music Recommender
Tutorial (Lamere & Celma)*



How?

How?

- Version 1 – One feature vector per song
 - High-level features extracted from data
 - Timbral (MFCCs, etc), Rhythmic content (beat histogram, autocor, tempos), Pitch info
 - Sampling of the frames in the song
 - Statistics of features extracted from a piece (includes means, weights, etc)
 - Representative of MFCC spectral shape
 - Could further use “Anchor space” where classifiers are training to represent musically meaningful classifiers. (Euclidean distance between anchor space)

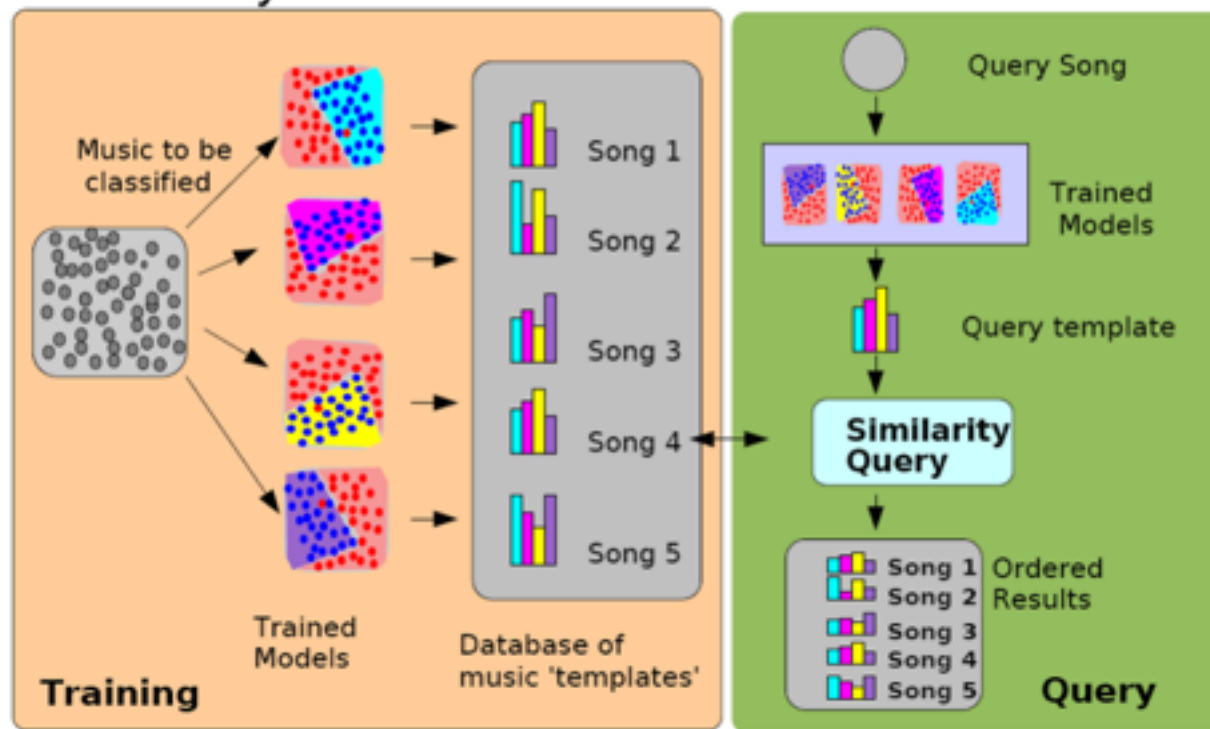
How?

- Version 1 – One feature vector per song
 - High-level features extracted from data
 - Timbral (MFCCs, etc), Rhythmic content (beat histogram, autocor, tempos), Pitch info
 - Sampling of the frames in the song
 - Statistics of features extracted from a piece (includes means, weights, etc)
 - Representative of MFCC spectral shape
 - Could further use “Anchor space” where classifiers are training to represent musically meaningful classifiers. (Euclidean distance between anchor space)
- Version 2 – Cloud of points
 - Extract audio every N frames
 - K-Means or GMM representing a “cloud of points” for song
 - Clusters: mean, covariance and weight of each cluster = signature for song/artist/genre

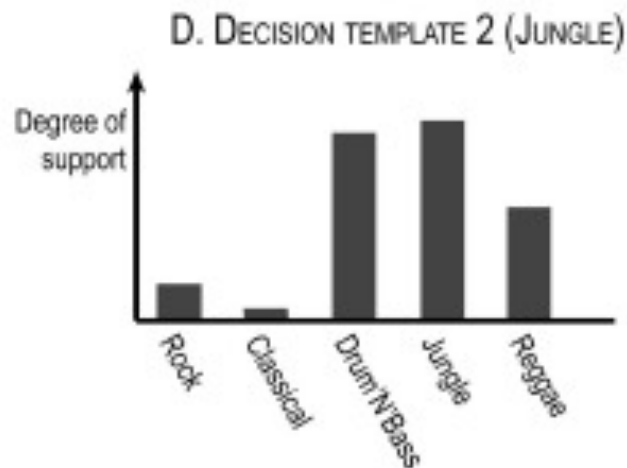
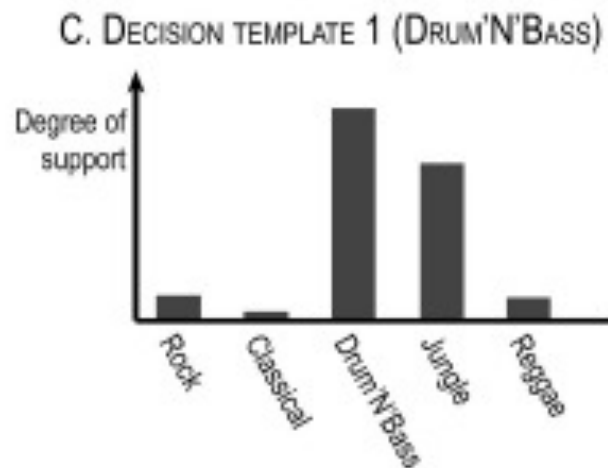
Music Recommendation

- Cloud of points from frames of song
 - High-level features extracted from data
 - Classifier: Weighted attribute nearest neighbors or fast distance measures.
 - k-Means or GMM used to create clusters.
 - The mean, covariance and weight of each cluster = signature for the song.
- Compare distance between other songs (signature) using various techniques to measure distance between probability distributions. (Most similar = closest distance)

- Automatic annotation
 - ❖ Similarity based on classification

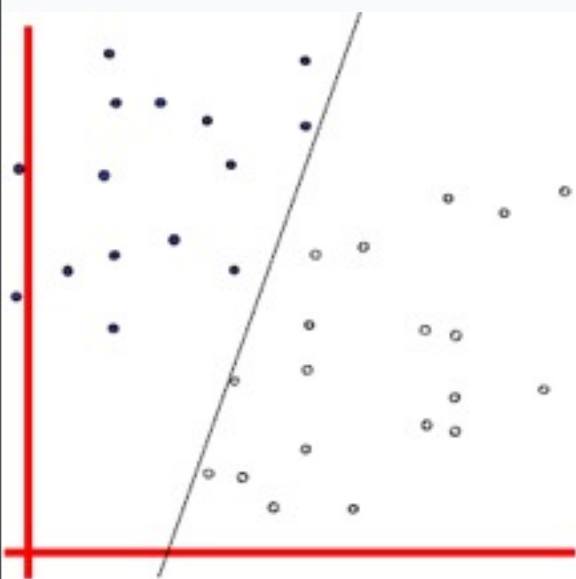


From ISMIR 2007 Music Recommender Tutorial (Lamere & Celma)

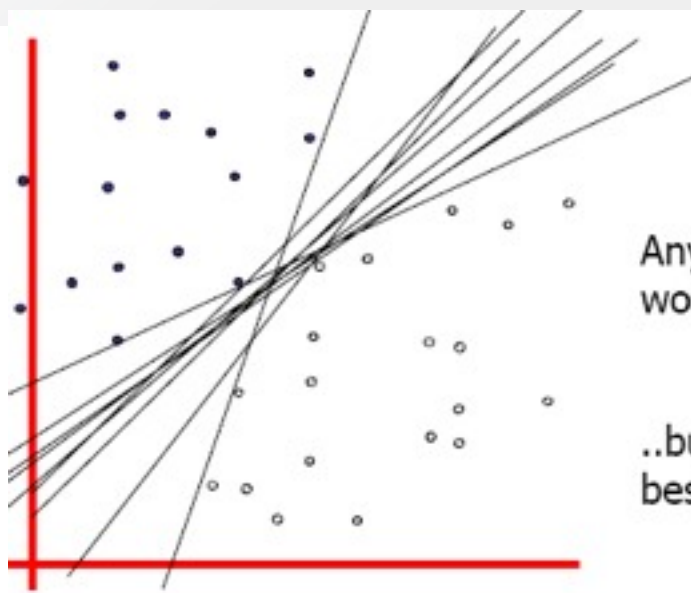




SUPPORT VECTOR MACHINES (SVM)



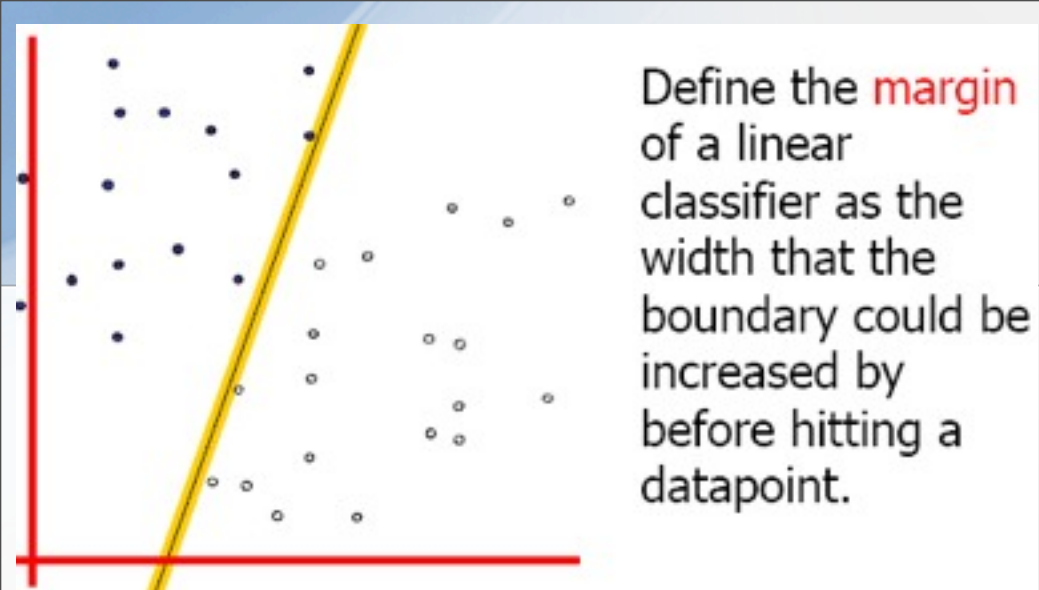
How would you
classify this data?



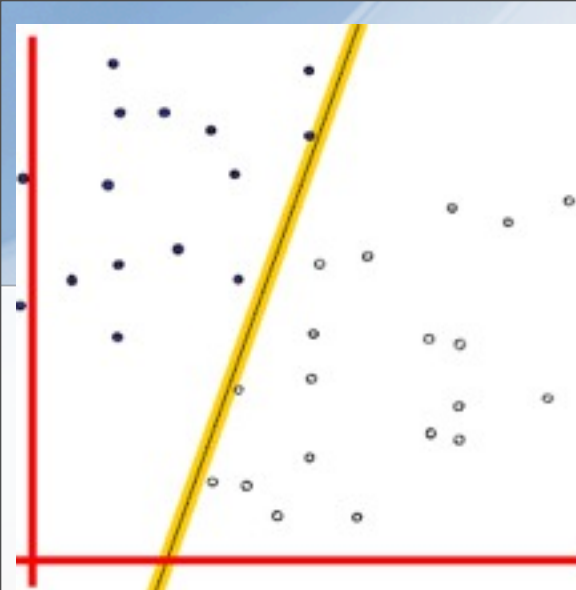
Any of these
would be fine..

..but which is
best?

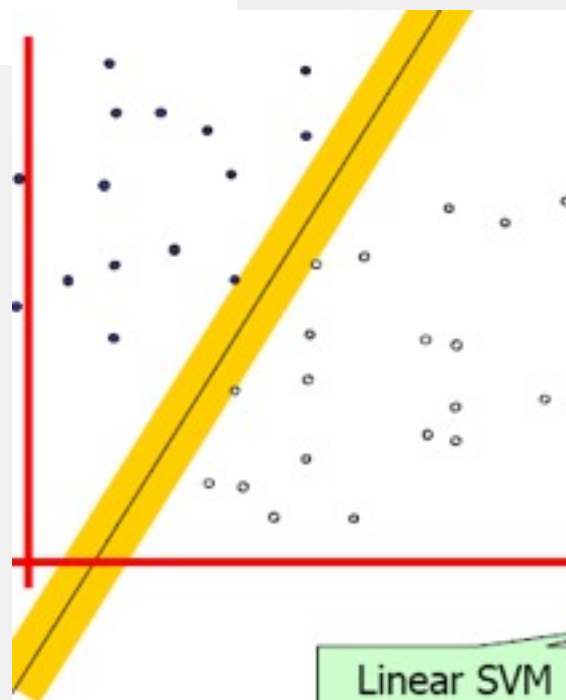
From : <http://www.autonlab.org/tutorials/>



From : <http://www.autonlab.org/tutorials/>



Define the **margin** of a linear classifier as the width that the boundary could be increased by before hitting a datapoint.



The **maximum margin linear classifier** is the linear classifier with the, um, maximum margin.

This is the simplest kind of SVM (Called an LSVM)

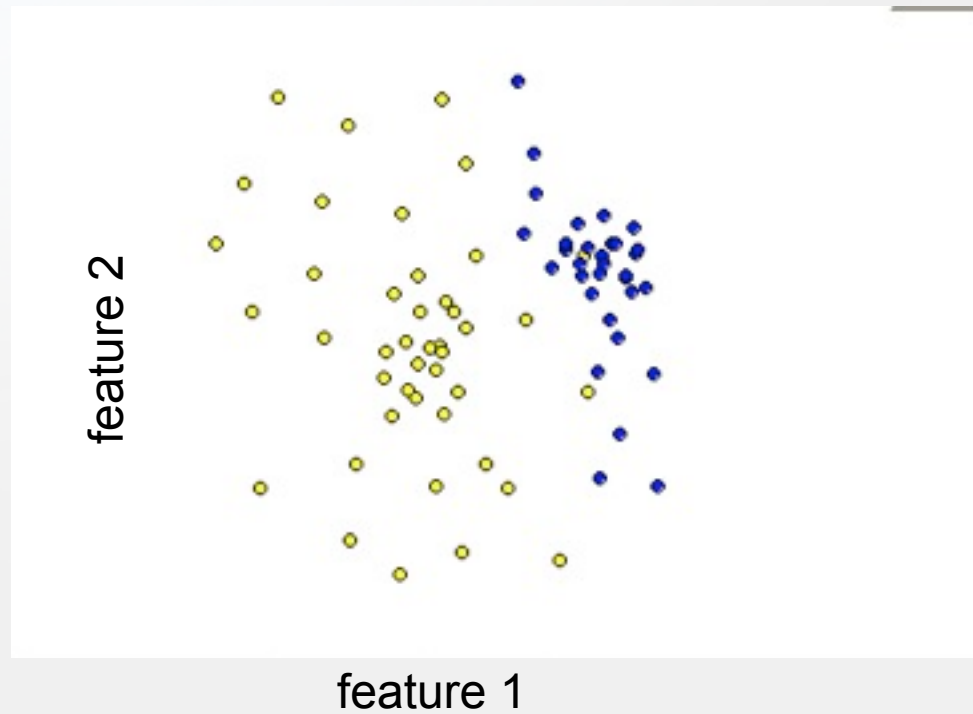
From : <http://www.autonlab.org/tutorials/>

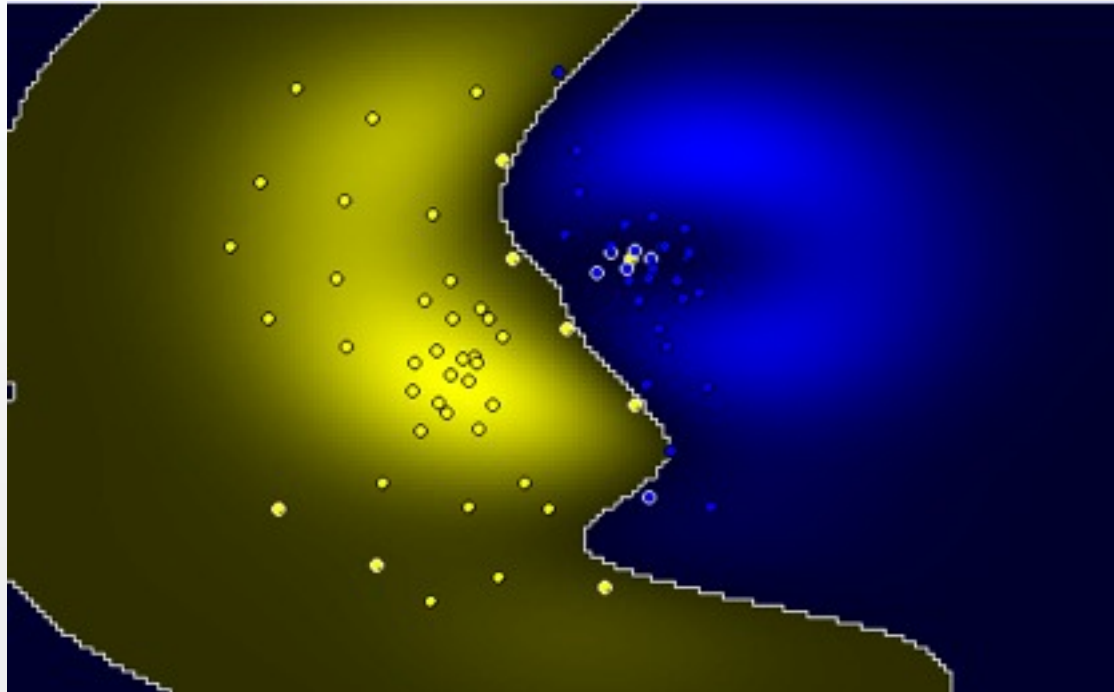
SVM

- Hyperplane separates the data from the two classes with a “maximum margin”.
- Support Vectors – are those data points that the margin pushes up against
- SVM training is guaranteed to find the global minimum of the cost function.
- Less experience needed – fewer parameters to tune

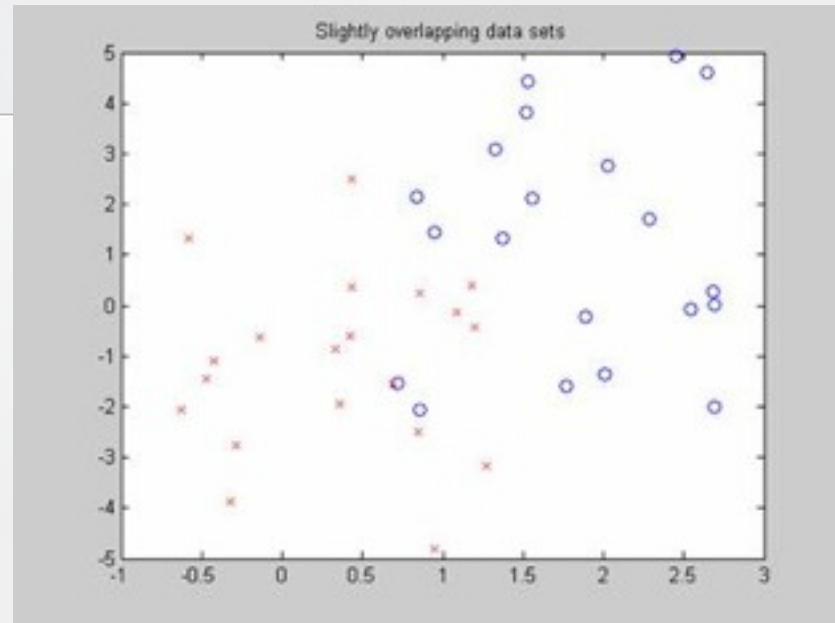
SVM with polynomial kernel visualization by Udi Aharoni

- <http://www.youtube.com/watch?v=3liCbRZPrZA>





SVM Parameters



What effect do the parameters of an radial-basis-function SVM have on the separating the two data sets?

Using the RBF kernel, we have to choose values of :

γ = degree of curviness of the hyperplane / complexity of the contour

C = allowance for points to overlap into each other's class

[Video 1](#)

[Video 2](#)

RBF Parameters: C and gamma

- Grid search using cross-validation to find the best one. Coarse then fine grid search.
- e.g., 2^{-5} , 2^{-3} , ... 2^{+15} , gamma = 2^{-15} , 2^{-13} , 2^{+3}

RBF Parameters: C and gamma

- Grid search using cross-validation to find the best one. Coarse then fine grid search.
- e.g., 2^{-5} , 2^{-3} , ... 2^{+15} , $\text{gamma} = 2^{-15}$, 2^{-13} , 2^{+3}
- Why grid search
 - Psychological (If you have time for brute force... why chance it on approximations or heuristics)
 - Since there are only 2 params, grid search isn't all that different from advanced estimation techniques
 - Easily parallelized (C and gamma are

Practical Guide to SVM: The Lab

- Feature selection?
- Scale feature data
 - Save scaling stats so we can scale the test data to be in the same range
- Feature format
- Class labels $\{1, -1\}$ or $\{0, 1\}$
- Kernels (linear, polynomial, RBF, sigmoid)
- Find best C and γ (cross-validation)
- Train with entire training set
- Test with validation or test set

- `easy.py` or `grid.py`